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Introduction to Measurement Error

Jose Pina-Sánchez

David Buil-Gil

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- What is measurement error?
 - any discrepancy between the ‘true’ and the observed value
 - the result of poorly defined construct and/or an imperfect measurement process

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- What is measurement error?
 - any discrepancy between the ‘true’ and the observed value
 - the result of poorly defined construct and/or an imperfect measurement process
- Why does it matter?
 - we cannot describe reality accurately
 - e.g. What is the true extent of property crime? What is the true prevalence of covid? Has it increased compared to last year? Is it higher in Leeds than in Bradford?
 - measurement error can also bias causal inference
 - e.g. Does education affect violent crime? Does crime affect property values?

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- What is measurement error?
 - any discrepancy between the ‘true’ and the observed value
 - the result of poorly defined construct and/or an imperfect measurement process
- Why does it matter?
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e.g. What is the true extent of property crime? What is the true prevalence of covid? Has it increased compared to last year? Is it higher in Leeds than in Bradford?
 - measurement error can also bias causal inference
e.g. Does education affect violent crime? Does crime affect property values?
- There are ways to anticipate its impact
 - and to some extent adjust for it
 - but to do so we first need to define these errors formally

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- The classical measurement error model (random errors)

$$- \underbrace{\widehat{X^*}}^{\text{observed}} = \underbrace{\widehat{X}}^{\text{true value}} + \underbrace{\widehat{U}}^{\text{noise}}$$

- with the errors taken to be randomly distributed, $U \sim N(0, \sigma_U)$



- e.g. results from a math test, blood pressure readings

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- The classical measurement error model (random errors)

$$\underbrace{\text{observed}}_{X^*} = \underbrace{\text{true value}}_X + \underbrace{\text{noise}}_U$$

- with the errors taken to be randomly distributed, $U \sim N(0, \sigma_U)$



- e.g. results from a math test, blood pressure readings
- Only the variance is affected
 - $\sigma_{X^*}^2 = \sigma_X^2 + \sigma_U^2$; but the mean is unaffected since $E(U) = 0$
 - taking repeated observations we can estimate the prevalence of classical measurement error
 - the reliability ratio: $\rho_{X^*} = \frac{\sigma_X^2}{\sigma_X^2 + \sigma_U^2} = \frac{\text{true variability}}{\text{observed variability}}$

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- The classical model is the most commonly invoked
 - it is simple and reflects well enough some measurement processes, but not all

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- The classical model is the most commonly invoked
 - it is simple and reflects well enough some measurement processes, but not all
- Measurement error is often *systematic*
 - $X^* = X + U$; but $E(U) \neq 0$



- e.g. self-reported spells of unemployment, police recorded crime

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- The classical model is the most commonly invoked
 - it is simple and reflects well enough some measurement processes, but not all
- Measurement error is often *systematic*
 - $X^* = X + U$; but $E(U) \neq 0$



- e.g. self-reported spells of unemployment, police recorded crime
- Repeated observations won't detect systematic errors
 - we need a *gold standard*
 - e.g. unemployment register, victimisation surveys

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- What if the error is proportional to the true value of the quantity being measured?
 - e.g. memory failures, count data
 - How many alcohol units do you drink per week?*
 - How many partners have you had in your life?*

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- What if the error is proportional to the true value of the quantity being measured?
 - e.g. memory failures, count data
 - How many alcohol units do you drink per week?*
 - How many partners have you had in your life?*
- These can be better specified using a multiplicative rather than an additive model
 - $X^* = X \cdot U$, rather than $X^* = X + U$,
with $E(U) = 1$ if random, and $E(U) \neq 1$ if systematic



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- Misclassification (for discrete data)
 - e.g. ethnicity determined through individuals' names

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- Heteroskedastic errors (their variance is not constant)
 - e.g. recall errors that increase with the age of the subject

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- Misclassification (for discrete data)
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 - e.g. recall errors that increase with the age of the subject
- Autocorrelated errors (they are correlated with each other)
 - in spatial and longitudinal data; e.g. interviewer effects

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- Heteroskedastic errors (their variance is not constant)
 - e.g. recall errors that increase with the age of the subject
- Autocorrelated errors (they are correlated with each other)
 - in spatial and longitudinal data; e.g. interviewer effects
- Differential errors (correlated with the cause or the effect)

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- Different forms of measurement error can affect univariate stats
 - random errors affect measures of dispersion, systematic errors affect measures of centrality

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- Different forms of measurement error can affect univariate stats
 - random errors affect measures of dispersion, systematic errors affect measures of centrality
- But how does measurement error affect estimates from multivariate (regression) models?

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- Let's review some scenarios for the case of simple linear regression

$$- Y = \alpha + \beta X + \epsilon$$

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- Let's review some scenarios for the case of simple linear regression

$$- Y = \alpha + \beta X + \epsilon$$

- ① Random additive errors affecting the response variable

$$- Y^* = Y + U, \text{ and } U \sim N(0, \sigma_U)$$

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$$- X^* = X + U, \text{ and } U \sim N(0, \sigma_U)$$

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- ③ Systematic additive errors affecting the response variable

$$- Y^* = Y + U, \text{ and } E(U) \neq 0$$

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- ④ Systematic multiplicative errors affecting the response variable

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- ④ Systematic multiplicative errors affecting the response variable

$$- Y^* = Y \cdot U, \text{ and } E(U) \neq 1$$

- **Question:** Is β biased in any of those scenarios?

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- Scenario 1: random additive errors on the response

$$- Y^* = \alpha + \beta X + \epsilon, \text{ with } Y^* = Y + U, \text{ and } U \sim N(0, \sigma_U)$$

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$$Y + U = \alpha + \beta X + \epsilon$$

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- Scenario 1: random additive errors on the response
 - $Y^* = \alpha + \beta X + \epsilon$, with $Y^* = Y + U$, and $U \sim N(0, \sigma_U)$

$$Y + U = \alpha + \beta X + \epsilon$$

$$Y = \alpha + \beta X + (\epsilon - U)$$
 - the measurement error is absorbed by the model's error term, affecting precision, but leaving regression coefficients unbiased

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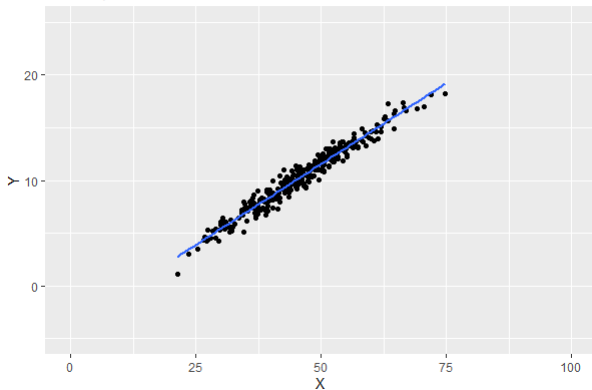
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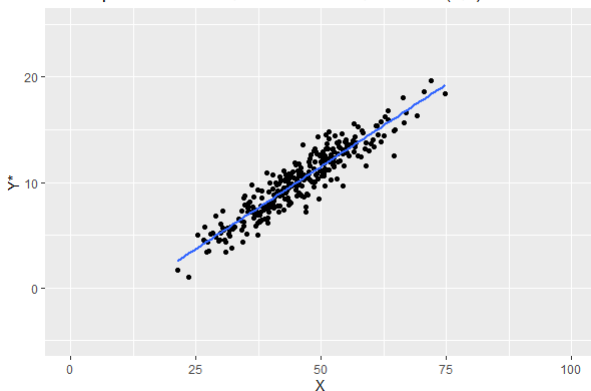
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Scatterplot for Y^* and X , where $Y^* = Y + U$, and $U \sim N(0, 1)$



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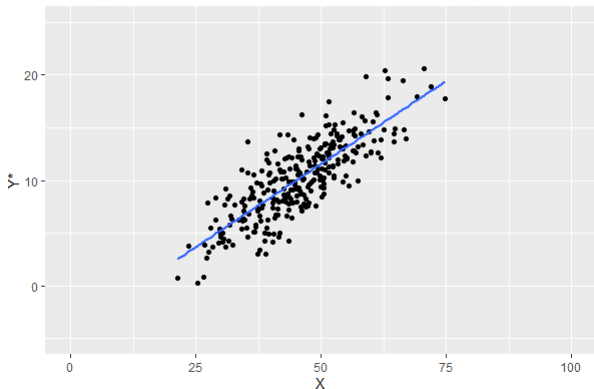
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Scatterplot for Y^* and X , where $Y^*=Y+U$, and $U\sim N(0,2)$



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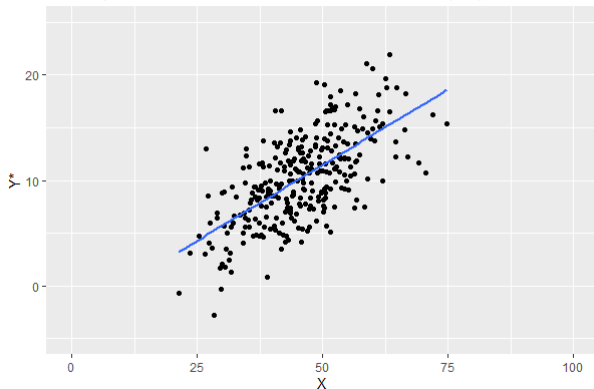
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Scatterplot for Y^* and X , where $Y^*=Y+U$, and $U \sim N(0,3)$



- Scenario 2: random additive errors on the covariate
 - $Y = \alpha + \beta X^* + \epsilon$, with $X^* = X + U$, and $U \sim N(0, \sigma_U)$

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- Scenario 2: random additive errors on the covariate
 - $Y = \alpha + \beta X^* + \epsilon$, with $X^* = X + U$, and $U \sim N(0, \sigma_U)$
 - Using OLS we can estimate α and β solving...

$$\begin{cases} \hat{\alpha} = \bar{Y} - \hat{\beta} \bar{X} \\ \hat{\beta} = \frac{\sigma_{X,Y}}{\sigma_X^2} \end{cases}$$

- Scenario 2: random additive errors on the covariate
 - $Y = \alpha + \beta X^* + \epsilon$, with $X^* = X + U$, and $U \sim N(0, \sigma_U)$

- Using OLS we can estimate α and β solving...

$$\begin{cases} \hat{\alpha} = \bar{Y} - \hat{\beta}\bar{X} \\ \hat{\beta} = \frac{\sigma_{X,Y}}{\sigma_X^2} \end{cases}$$

- If instead we have...

$$\begin{cases} \hat{\alpha}^* = \bar{Y} - \hat{\beta}^*\bar{X}^* \\ \hat{\beta}^* = \frac{\sigma_{X^*,Y}}{\sigma_{X^*}^2} \end{cases}$$

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 - $Y = \alpha + \beta X^* + \epsilon$, with $X^* = X + U$, and $U \sim N(0, \sigma_U)$

- Using OLS we can estimate α and β solving...

$$\begin{cases} \hat{\alpha} = \bar{Y} - \hat{\beta}\bar{X} \\ \hat{\beta} = \frac{\sigma_{X,Y}}{\sigma_X^2} \end{cases}$$

- If instead we have...then..

$$\begin{cases} \hat{\alpha}^* = \bar{Y} - \hat{\beta}\bar{X}^* = \bar{Y} - \hat{\beta}\bar{X} = \hat{\alpha}; & \text{unbiased constant} \\ \hat{\beta}^* = \frac{\sigma_{X^*,Y}}{\sigma_{X^*}^2} \end{cases}$$

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• Scenario 2: random additive errors on the covariate

– $Y = \alpha + \beta X^* + \epsilon$, with $X^* = X + U$, and $U \sim N(0, \sigma_U)$

– Using OLS we can estimate α and β solving...

$$\begin{cases} \hat{\alpha} = \bar{Y} - \hat{\beta} \bar{X} \\ \hat{\beta} = \frac{\sigma_{X,Y}}{\sigma_X^2} \end{cases}$$

– If instead we have X^* , then..

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• Scenario 2: random additive errors on the covariate

– $Y = \alpha + \beta X^* + \epsilon$, with $X^* = X + U$, and $U \sim N(0, \sigma_U)$

– Using OLS we can estimate α and β solving...

$$\begin{cases} \hat{\alpha} = \bar{Y} - \hat{\beta} \bar{X} \\ \hat{\beta} = \frac{\sigma_{X,Y}}{\sigma_X^2} \end{cases}$$

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Using the properties of the covariance and the variance we can see how the former is not affected by random noise, but the latter is:

$$\sigma_{X^*,Y} = \sigma_{X+U,Y} = \sigma_{X,Y} + \sigma_{U,Y} = \sigma_{X,Y}$$

$$\sigma_{X^*}^2 = \sigma_{X+U}^2 = \sigma_X^2 + \sigma_U^2 + \sigma_{X,U} = \sigma_X^2 + \sigma_U^2$$

– We can see this effect using simulated data

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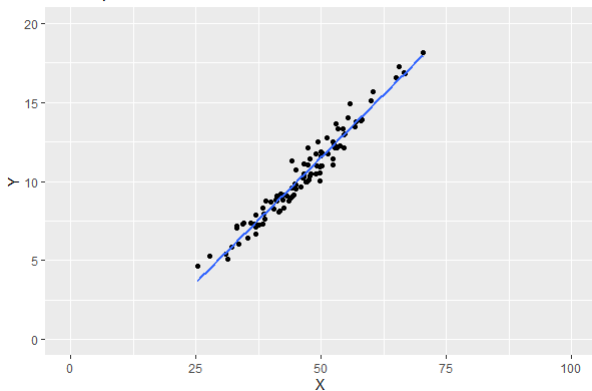
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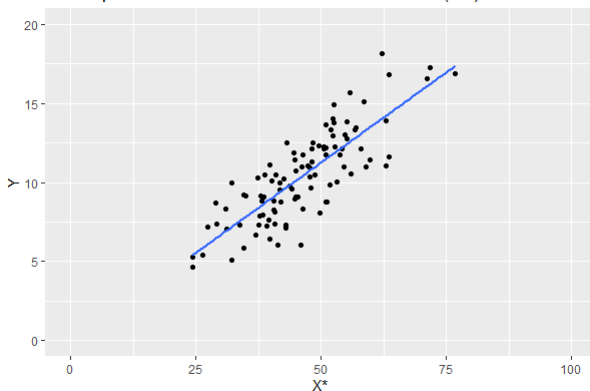
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Scatterplot for Y and X^* , where $X^*=X+U$, and $U \sim N(0,5)$



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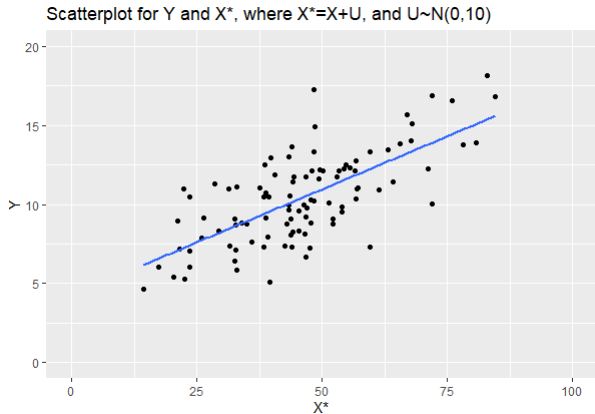
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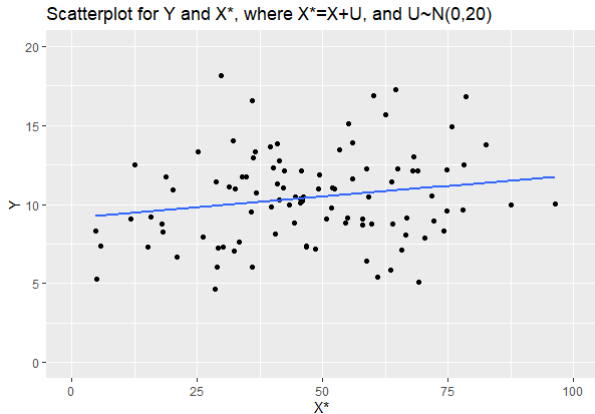
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- Scenario 3: systematic additive errors on the response
 - $Y^* = \alpha + \beta X + \epsilon$, with $Y^* = Y + U$, and $E(U) \neq 0$

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$$Y + U = \alpha + \beta X + \epsilon$$

$$Y = (\alpha - U) + \beta X + \epsilon$$

- the constant is biased, but the slope is not

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- the constant is biased, but the slope is not

- Scenario 4: systematic multiplicative errors on the response

- $Y^* = \alpha + \beta X + \epsilon$, with $Y^* = Y \cdot U$, and $E(U) \neq 1$

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- Scenario 3: systematic additive errors on the response

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$$Y + U = \alpha + \beta X + \epsilon$$

$$Y = (\alpha - U) + \beta X + \epsilon$$

- the constant is biased, but the slope is not

- Scenario 4: systematic multiplicative errors on the response

- $Y^* = \alpha + \beta X + \epsilon$, with $\underline{Y^* = Y \cdot U}$, and $E(U) \neq 1$

$$Y \cdot U = \alpha + \beta X + \epsilon$$

$$Y = \frac{\alpha + \beta X + \epsilon}{U}$$

- all regression coefficients are biased

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 - from relatively negligible to ‘all is wrong!’
 - even when the errors are completely random

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